

## BEGINNING OF LECTURE 4

## 2.B Bases

span + linear independence = basis

**Definition 13.**  $v_1, \dots, v_n \in V$  is a basis of  $V$  if  $\text{span}(v_1, \dots, v_n) = V$  and  $v_1, \dots, v_n$  are linearly independent.

**Proposition 12.**  $v_1, \dots, v_n \in V$  is a basis of  $V$  if and only if  $\forall v \in V, \exists! a_1, \dots, a_n \in \mathbb{F}$  such that

$$v = a_1 v_1 + \dots + a_n v_n$$

The notion of a basis is extremely important because it allows us to define a coordinate system for our vector spaces!

Examples:

1.  $(1, 0, \dots, 0), (0, 1, 0, \dots, 0), \dots, (0, \dots, 0, 1)$  is the standard basis of  $\mathbb{F}^n$ .
2.  $1, z, \dots, z^m$  is the standard basis for  $\mathcal{P}_m(\mathbb{F})$
3. Let  $\mathbb{Z}_N = \{0, 1, \dots, N-1\}$  (with addition mod  $N$ ) and let  $V = \{f : \mathbb{Z}_N \rightarrow \mathbb{C}\}$ . The standard (time side) basis for  $V$  is  $\delta_0, \dots, \delta_{N-1}$  where

$$\delta_k(n) = \begin{cases} 1 & n = k \\ 0 & n \neq k \end{cases}$$

Indeed,

$$f(n) = \sum_{k=0}^{N-1} f(k) \delta_k(n)$$

Fourier analysis tells us that another (frequency side) basis for  $V$  is  $e_0, \dots, e_{N-1}$  where

$$e_k(n) = \frac{1}{\sqrt{N}} e^{2\pi i k n / N}$$

and

$$f(n) = \sum_{k=0}^{N-1} a_k e_k(n)$$

with

$$a_k = \hat{f}(k) = \frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} f(n) e^{-2\pi i k n / N}$$

The coefficients  $a_k$  define the function  $\hat{f}(k)$  which is the Fourier transform of  $f$ .

If  $v_1, \dots, v_n$  spans  $V$ , it should have enough vectors to make a basis. Indeed:

**Proposition 13.** *If  $\mathcal{L} = v_1, \dots, v_n$  spans  $V$ , then  $\mathcal{L}$  can be reduced to a basis.*

*Proof.* If  $\mathcal{L}$  is linearly independent, then we are done. So assume it is not. We will selectively throw away vectors using the LDL.

Step 1: If  $v_1 = 0$  remove  $v_1$

Step 2: If  $v_2 \in \text{span}(v_1)$ , remove  $v_2$

Step  $k$ : If  $v_k \in \text{span}(v_1, \dots, v_{k-1})$ , remove  $v_k$

Stop at Step  $n$ , getting a new list  $\mathcal{L}^* = w_1, \dots, w_m$ . We still have  $\text{span}(\mathcal{L}^*) = V$  since we only discarded vectors that were in the span of other vectors. We also have the property:

$$w_k \notin \text{span}(w_1, \dots, w_{k-1}), \quad \forall k > 1$$

Thus by the contrapositive of LDL,  $\mathcal{L}^*$  is linearly independent, and hence a basis.  $\square$

**Corollary 1.** *If  $V$  is finite dimensional, it has a basis.*

We just removed stuff from a spanning set to get a basis. We can also add stuff to a linearly independent set to get a basis.

**Proposition 14.** *If  $\mathcal{L} = u_1, \dots, u_m \in V$  is linearly independent, then  $\mathcal{L}$  can be extended to a basis.*

*Proof.* Let  $w_1, \dots, w_n$  be a basis of  $V$ . Thus

$$\mathcal{L}^* = u_1, \dots, u_m, w_1, \dots, w_n$$

spans  $V$ . Apply the procedure in the proof of Proposition 13, and note that none of the  $u$ 's get deleted [why?].  $\square$

Now we show that every subspace  $U$  has a complementary subspace  $W$  that together direct sum to  $V$ .

**Proposition 15.** *Suppose  $V$  is finite dimensional and that  $U$  is a subspace of  $V$ . Then there exists another subspace  $W$  such that*

$$V = U \oplus W$$

*Proof.*  $V$  finite dimensional  $\Rightarrow U$  finite dimensional  $\Rightarrow U$  has a basis  $u_1, \dots, u_m$ . By the previous proposition we can extend  $u_1, \dots, u_m$  to a basis of  $V$ , say  $\mathcal{L} = u_1, \dots, u_m, w_1, \dots, w_n$ . We show that  $W = \text{span}(w_1, \dots, w_n)$  is the answer.

We need to show: (1)  $V = U + W$ , and (2)  $U \cap W = \{0\}$ . Since  $\mathcal{L}$  is a basis, for any  $v \in V$  we have:

$$v = \underbrace{a_1u_1 + \dots + a_mu_m}_{u \in U} + \underbrace{b_1w_1 + \dots + b_nw_n}_{w \in W} = u + w \in U + W$$

Now suppose that  $v \in U \cap W$ . Then

$$v = a_1u_1 + \dots + a_mu_m = b_1w_1 + \dots + b_nw_n$$

which implies

$$a_1u_1 + \dots + a_mu_m - b_1w_1 - \dots - b_nw_n = 0$$

But  $\mathcal{L}$  is linearly independent so  $a_1 = \dots = a_m = b_1 = \dots = b_n = 0$ . □

## 2.C Dimension

Since a basis gives a unique representation of each  $v \in V$ , we should be able to say that the number of vectors in basis is the dimension of  $V$ . But to do so, we need to make sure every basis of  $V$  has the same number of vectors. Indeed:

**Theorem 2.** *Any two bases of a finite dimensional vector space have the same length.*

*Proof.* Let  $\mathcal{B}_1 = v_1, \dots, v_m$  and  $\mathcal{B}_2 = w_1, \dots, w_n$  be two bases of  $V$ . Since  $\mathcal{B}_1$  is linearly independent and  $\mathcal{B}_2$  spans  $V$ ,  $m \leq n$ . Flipping the roles of  $\mathcal{B}_1$  and  $\mathcal{B}_2$ , we get  $n \leq m$ . □

**Definition 14.** The dimension of  $V$  is the length of  $\mathcal{B}$  for any basis  $\mathcal{B}$ .

**Proposition 16.** *If  $U$  is a subspace of  $V$ , then  $\dim U \leq \dim V$*

Examples:

1.  $\dim \mathbb{F}^n = n$

Remark:  $\dim \mathbb{R}^2 = 2$  and  $\dim \mathbb{C} = 1$ , even though  $\mathbb{R}^2$  can be identified with  $\mathbb{C}$ . The scalar field  $\mathbb{F}$  cannot be ignored when computing the dimension of  $V$ !

2.  $\dim \mathcal{P}_m(\mathbb{F}) = m + 1$

Let  $\mathcal{L} = v_1, \dots, v_n$ . If  $\dim V = n$ , then we need only check if  $\mathcal{L}$  is linearly independent OR if  $\text{span}(\mathcal{L}) = V$  to conclude that  $\mathcal{L}$  is a basis for  $V$ .

**Proposition 17.** *Suppose  $\dim V = n$  and let  $\mathcal{L} = v_1, \dots, v_n$ .*

1. *If  $\mathcal{L}$  is linearly independent, then  $\mathcal{L}$  is a basis*

2. *If  $\text{span}(\mathcal{L}) = V$ , then  $\mathcal{L}$  is a basis.*

*Proof.* Use Proposition 14 for (1) and Proposition 13 for (2). □

END OF LECTURE 4