

## Lecture 20: Time-Frequency Analysis of Stationary Processes

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**Definition 5.20.** The power spectral density of a second order stationary process  $X$  is the Fourier transform of  $R_X(\tau)$ , that is,  $\widehat{R}_X(\omega)$ .

For a stationary process  $X$ , the function  $R_X(\tau) = \text{Cov}_X(0, \tau)$  measures the variability of random fluctuations of  $X$  over time. The power spectral density organizes the total variability of  $X$  over all times into different frequency components. A time frequency transforms of a stationary process allow us to measure the variability of  $X$  within time-frequency Heisenberg boxes. For example, the wavelet coefficients of  $X$  define a family of new stochastic processes  $X * \psi_s$ , indexed by the scale parameter  $s > 0$ , which are defined as

$$WX(u, s) = X * \psi_s(u) = \int_{\mathbb{R}} X(t) \psi_s(u - t) dt$$

We assume  $\psi_s(t)$  is continuous, real valued, and compactly supported. Note the integral of a stochastic process with continuous sample paths times a continuous deterministic function  $f(t)$ , over a finite interval, is a random variable defined using the Riemann integral:

$$\int_a^b X(t) f(t) dt = \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} X(t_i^n) f(t_i^n) (t_{i+1}^n - t_i^n)$$

where  $a = t_0^n < t_1^n < \dots < t_{n-1}^n < t_n^n = b$  for all  $n$ , and  $\delta_n = \max_{0 \leq i \leq n-1} |t_{i+1}^n - t_i^n| \rightarrow 0$  as  $n \rightarrow \infty$ . The new stochastic process  $X * \psi_s = (X * \psi_s(u))_{u \in \mathbb{R}}$  retains only the fluctuations of  $X$  at the scale  $s$ , for each time  $u$ ; smaller and larger scale fluctuations are eliminated because the wavelet  $\psi_s$  has a frequency support essentially supported in a frequency band determined by the scale  $s$ . The next proposition encodes this statement more precisely.

**Theorem 5.21.** Let  $X$  be a second order stationary process with continuous sample paths and with mean zero, i.e.,  $\mathbb{E}[X] = 0$ , and let  $\psi$  be a continuous real valued wavelet with compact support. Then  $X * \psi_s$  is a stationary process for each  $s > 0$  and:

$$\widehat{R}_{X * \psi_s}(\omega) = \widehat{R}_X(\omega) |\widehat{\psi}_s(\omega)|^2 = s |\widehat{\psi}(s\omega)|^2 \widehat{R}_X(\omega) \quad (52)$$

*Proof.* The fact that  $X * \psi_s$  is stationary is straightforward. We also note that since  $\mathbb{E}[X] = 0$ , we also have  $\mathbb{E}[X * \psi_s] = 0$  for each  $s > 0$ . Thirdly, if  $R_X \in \mathbf{L}^1(\mathbb{R})$  then  $R_{X * \psi_s} \in \mathbf{L}^1(\mathbb{R})$ ;

indeed:

$$\begin{aligned}
\int_{\mathbb{R}} |R_{X*\psi_s}(\tau)| d\tau &= \int_{\mathbb{R}} |\mathbb{E}[X * \psi_s(0)X * \psi_s(\tau)]| d\tau \\
&= \int_{\mathbb{R}} \left| \mathbb{E} \left[ \int_{\mathbb{R}} X(u)\psi_s(-u) du \cdot \int_{\mathbb{R}} X(v)\psi_s(\tau - v) dv \right] \right| d\tau \\
&= \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \int_{\mathbb{R}} \mathbb{E}[X(u)X(v)]\psi_s(-u)\psi_s(\tau - v) du dv \right| d\tau \\
&= \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \int_{\mathbb{R}} R_X(u - v)\psi_s(-u)\psi_s(\tau - v) du dv \right| d\tau \quad (\text{CoV: } t = u - v) \\
&= \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \int_{\mathbb{R}} R_X(t)\psi_s(-(t + v))\psi_s(\tau - v) dt dv \right| d\tau \\
&= \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \psi_s(\tau - v) \int_{\mathbb{R}} R_X(t)\psi_s(-v - t) dt dv \right| d\tau \\
&= \int_{\mathbb{R}} \left| \int_{\mathbb{R}} \psi_s(\tau - v)R_X * \psi_s(-v) dv \right| d\tau \\
&\leq \int_{\mathbb{R}} \int_{\mathbb{R}} |\psi_s(\tau - v)R_X * \psi_s(-v)| dv d\tau \\
&= \int_{\mathbb{R}} |R_X * \psi_s(-v)| \int_{\mathbb{R}} |\psi_s(\tau - v)| d\tau dv \\
&= \|\psi_s\|_1 \|R_X * \psi_s\|_1 \\
&\leq \|R_X\|_1 \|\psi_s\|_1^2
\end{aligned}$$

Since  $\psi$  is continuous and compactly supported, it is in  $\mathbf{L}^1(\mathbb{R})$  and so the bound is finite, and  $R_{X*\psi_s} \in \mathbf{L}^1(\mathbb{R})$ .

Now let us prove (52). Many of the steps are the same as above.

$$\begin{aligned}
\widehat{R}_{X*\psi_s}(\omega) &= \int_{\mathbb{R}} R_{X*\psi_s}(\tau) e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \mathbb{E}[X * \psi_s(0) X * \psi_s(\tau)] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \mathbb{E} \left[ \int_{\mathbb{R}} X(u) \psi_s(-u) du \cdot \int_{\mathbb{R}} X(v) \psi_s(\tau - v) dv \right] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} \int_{\mathbb{R}} \mathbb{E}[X(u)X(v)] \psi_s(-u) \psi_s(\tau - v) du dv \right] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} \int_{\mathbb{R}} R_X(u - v) \psi_s(-u) \psi_s(\tau - v) du dv \right] e^{-i\omega\tau} d\tau \quad (\text{CoV: } t = u - v) \\
&= \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} \int_{\mathbb{R}} R_X(t) \psi_s(-(t + v)) \psi_s(\tau - v) dt dv \right] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} \psi_s(\tau - v) \int_{\mathbb{R}} R_X(t) \psi_s(-v - t) dt dv \right] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} \psi_s(\tau - v) R_X * \psi_s(-v) dv \right] e^{-i\omega\tau} d\tau \\
&= \int_{\mathbb{R}} R_X * \psi_s(-v) \int_{\mathbb{R}} \psi_s(\tau - v) e^{-i\omega\tau} d\tau dv \\
&= \widehat{\psi}_s(\omega) \int_{\mathbb{R}} R_X * \psi_s(-v) e^{-i\omega v} dv \\
&= \widehat{\psi}_s(\omega) \widehat{R}_x^*(\omega) \widehat{\psi}_s^*(\omega) \\
&= \widehat{R}_X(\omega) |\widehat{\psi}_s(\omega)|^2
\end{aligned}$$

where the last equality follows from recalling that  $R_X(\tau)$  is an even function, and hence its Fourier transform is real valued.  $\square$

Stationarity is a pretty strict assumption, and as mentioned, does not include the Wiener process. The notion of a stochastic process with stationary increments relaxes this requirement and includes a much larger number of stochastic processes.

**Definition 5.22.** A stochastic process  $X$  has stationary increments if, for all  $u \in \mathbb{R}$ , the stochastic process  $(X(t + u) - X(u))_{t \in \mathbb{R}}$  has the same distribution as  $(X(t) - X(0))_{t \in \mathbb{R}}$ .

Stochastic processes with stationary increments include many more processes than just stationary processes, which allows us to model a wider variety of phenomena. Note, in particular, if  $X$  has stationary increments then the mean and variance of an increment depends only on the length of the increment, not where it started. That is for any  $u \in \mathbb{R}$ ,

$$\begin{aligned}
\mathbb{E}[X(t + u) - X(u)] &= \mathbb{E}[X(t) - X(0)] \\
\text{Var}(X(t + u) - X(u)) &= \text{Var}(X(t) - X(0))
\end{aligned}$$

An example of a stochastic process with stationary increments is the Wiener process.

**Theorem 5.23.** *The Wiener process,  $W$ , has stationary increments.*

*Proof.* Define the stochastic process  $(\widetilde{W}(t))_{t \in \mathbb{R}}$  as

$$\widetilde{W}(t) = W(t + u) - W(u)$$

where  $u \in \mathbb{R}$  is fixed but arbitrary. Our goal is to show distribution of  $\widetilde{W}$  does not depend on  $u$ , which would mean that  $W$  has stationary increments. We first note the Wiener process,  $W$ , is a Gaussian process, and thus so is  $\widetilde{W}$ . Therefore, if we can show the mean function and the covariance function of  $\widetilde{W}$  do not depend on  $u$  then we are finished. For the mean function we have

$$m_{\widetilde{W}}(t) = \mathbb{E}[\widetilde{W}(t)] = \mathbb{E}[W(t + u)] - \mathbb{E}[W(u)] = 0 - 0 = 0$$

which is obviously independent of  $u$ . For the covariance function we have:

$$\begin{aligned} 2\text{Cov}_{\widetilde{W}}(s, t) &= 2\mathbb{E}[\widetilde{W}(s)\widetilde{W}(t)] \\ &= 2\mathbb{E}[(W(s + u) - W(u))(W(t + u) - W(u))] \\ &= 2\mathbb{E}[W(s + u)W(t + u)] + 2\mathbb{E}[W(u)^2] - 2\mathbb{E}[W(u)W(s + u)] - 2\mathbb{E}[W(u)W(t + u)] \\ &= |s + u| + |t + u| - |t - s| + |u| + |u| - |u| - |u + s| + |s| - |u| - |t - u| + |t| \\ &= |t| + |s| - |t - s| \end{aligned}$$

which is also independent of  $u$ . □

Fractional Brownian motion [7, 8] is a generalization of Brownian motion (i.e., the Wiener process). It depends on a parameter  $H$ , which is called the Hurst parameter.

**Definition 5.24.** A stochastic process  $B_H = (B_H(t))_{t \in \mathbb{R}}$  is called a fractional Brownian motion (fBm) with Hurst parameter  $H \in (0, 1)$  if it satisfies the following:

- $B_H$  is a Gaussian process with  $B_H(0) = 0$
- $B_H(t)$  is continuous in  $t$
- $m_{B_H}(t) = \mathbb{E}[B_H(t)] = 0$  for all  $t \in \mathbb{R}$
- $\text{Cov}_{B_H}(s, t) = \frac{1}{2}(|s|^{2H} + |t|^{2H} - |t - s|^{2H})$  for all  $s, t \in \mathbb{R}$ .

Notice that when  $H = 1/2$  we obtain regular Brownian motion, i.e., the Wiener process. Figure 30 plots three sample paths of fBm for  $H = 0.75$ , while Figure 31 plots sample paths of fBm for  $H = 0.15, 0.55, 0.95$ .

First note, that like the Wiener process, fractional Brownian motion has stationary increments for any  $H \in (0, 1)$ . Indeed, the proof is essentially identical.

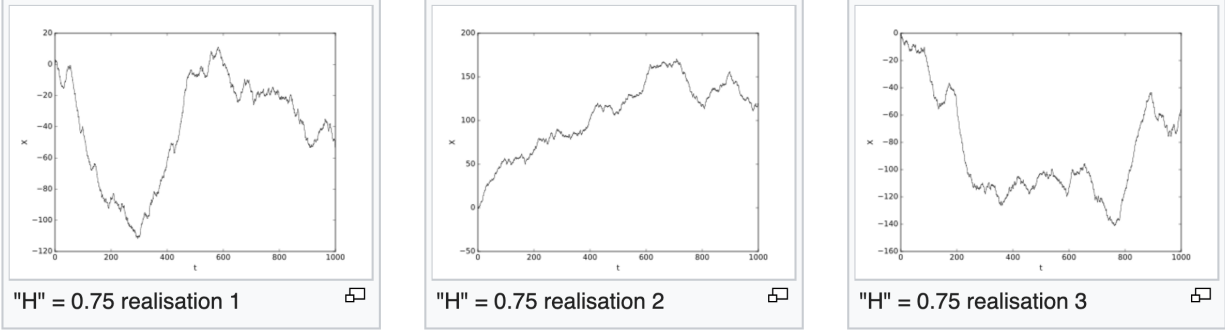


Figure 30: Three sample paths of fractional Brownian motion with Hurst parameter  $H = 0.75$ . Figure taken from [https://en.wikipedia.org/wiki/Fractional\\_Brownian\\_motion](https://en.wikipedia.org/wiki/Fractional_Brownian_motion).

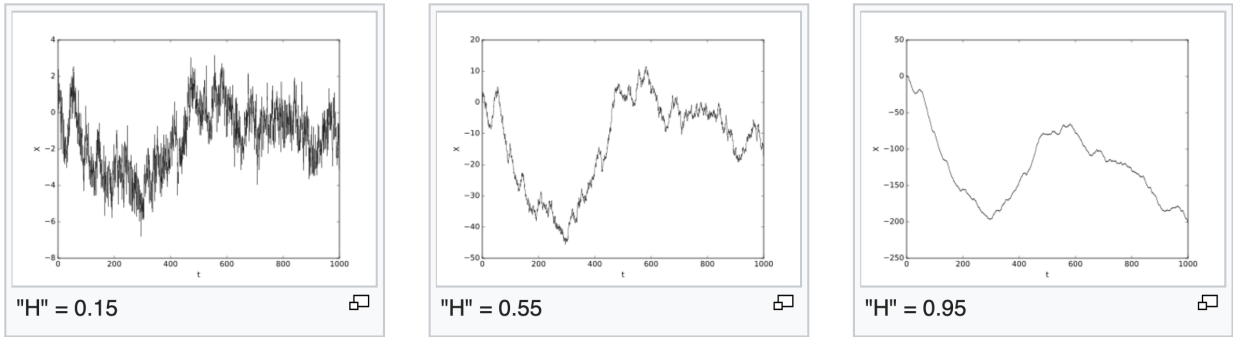


Figure 31: Sample paths of fractional Brownian motion with Hurst parameter  $H = 0.15$  (left),  $H = 0.55$  (middle), and  $H = 0.95$  (right). Figure taken from [https://en.wikipedia.org/wiki/Fractional\\_Brownian\\_motion](https://en.wikipedia.org/wiki/Fractional_Brownian_motion).

We also remark that fBm, and hence the Wiener process too, are self-similar. A stochastic process  $X = (X(t))_{t \in \mathbb{R}}$  is self-similar of order  $H$  if

$$\forall a > 0, \quad (X(at))_{t \in \mathbb{R}} \stackrel{d}{=} a^H (X(t))_{t \in \mathbb{R}}$$

From the definition of fBm we see it is self-similar, as its mean function satisfies

$$\mathbb{E}[B_H(at)] = 0 = \mathbb{E}[a^H B_H(t)]$$

and its covariance function satisfies

$$\begin{aligned} \mathbb{E}[B_H(as)B_H(at)] &= \frac{1}{2}(|as|^{2H} + |at|^{2H} - |as - at|^{2H}) \\ &= \frac{a^{2H}}{2}(|s|^{2H} + |t|^{2H} - |t - s|^{2H}) \\ &= \mathbb{E}[a^H B_H(s)a^H B_H(t)] \end{aligned}$$

Furthermore, since it is a Gaussian process, it is completely determined by its mean function and covariance function.

## References

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